

## CROSSING FAMILIES

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Given a set of points in the plane, a crossing family is a collection of line segments, each joining two of the points, such that any two line segments intersect internally. Two sets  $A$  and  $B$  of points in the plane are mutually avoiding if no line subtended by a pair of points in  $A$  intersects the convex hull of  $B$ , and vice versa. We show that any set of  $n$  points in general position contains a pair of mutually avoiding subsets each of size at least  $\sqrt{n/12}$ . As a consequence we show that such a set possesses a crossing family of size at least  $\sqrt{n/12}$ , and describe a fast algorithm for finding such a family.

## 1. Introduction

Consider  $n$  points in the plane in general position (no three points collinear). We say that a collection of line segments, each joining two of the given points, is a *crossing family* if every two segments intersect internally. In a natural variation the points belong to two color classes, and each segment of the crossing family joins points of different colors. We say that two equal-sized disjoint sets  $A$  and  $B$  can be *crossed* if there exists a crossing family exhausting  $A$  and  $B$  in which each line segment connects a point in  $A$  with a point in  $B$ .

In this paper we study crossing families. In Section 2 we show that  $\Omega(\sqrt{n})$ -size crossing families exist in both the colored and uncolored versions of the problem. Our proof is constructive, and yields an algorithm which can be implemented to find such a family in time  $O(n \log n)$ .

We obtain the result on crossing families by finding sets of points which are *mutually avoiding*. Say that a set  $A$  *avoids* a set  $B$  if no line (not line segment) subtended by a pair of points in  $A$  intersects the convex hull of  $B$ . This means that every vertex in  $B$  “sees” the points of  $A$  in the same order. The sets  $A$  and  $B$  are *mutually avoiding* if  $A$  avoids  $B$  and  $B$  avoids  $A$ . We show how to find mutually avoiding sets of size  $\Omega(\sqrt{n})$ . Valtr [7] has shown that this is best possible up to the

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constant. The result on crossing families then follows from showing that if a pair of sets  $A, B$  are mutually avoiding and of equal cardinalities then they can be crossed.

In Section 3 we characterize which pairs of sets are mutually avoiding and which can be crossed. This characterization shows that mutual avoidance is a much stronger notion than crossability, and supports our belief that the true size of a maximum crossing family grows more quickly than  $\sqrt{n}$ . (It could even be linear.) In Section 4 we show that the crossing family problem is equivalent to the problem of finding a collection of line segments which are pairwise “parallel”: i.e. the lines subtended by any pair of segments intersect beyond the segments.

The notions of avoidance and mutual avoidance extend naturally to higher dimensions: if  $A$  and  $B$  are sets of points in  $\mathbb{R}^d$ , then  $A$  avoids  $B$  if no hyperplane subtended by  $d$  points in  $A$  intersects the convex hull of  $B$ . In Section 5 we show that polynomial-sized mutually avoiding sets exist in arbitrary dimensions.

Several researchers have considered problems involving configurations of  $m$  line segments among  $n$  points in the plane. Alon and the second author [1] showed that if  $m \geq 6n - 5$  then there are always three mutually disjoint line segments. This was extended by the sixth author and Töröcsik [6] who showed that if  $m > k^4 n$  then there are  $k + 1$  mutually disjoint line segments. Capoteleas and the sixth author [2] showed that for  $k \leq n/2$  if the points are in convex position and  $m > (k - 1)(2n + 1 - 2k)$ , then there is a crossing family of size  $k$ , and that this is best possible.

## 2. Construction of an $\Omega(\sqrt{n})$ crossing family

In this section we show, given  $n$  points in general position in the plane, how to find a pair of mutually avoiding sets  $X'$  and  $Y'$  of size  $\Omega(\sqrt{n})$ . This is achieved by finding subsets  $X$  and  $Y$  such that  $X$  avoids  $Y$ , and then subsets  $X' \subseteq X$  and  $Y' \subseteq Y$  such that  $Y'$  avoids  $X'$ . Since a pair of equal-sized mutually avoiding sets can be crossed (see Corollary 1), we thus obtain a crossing family of cardinality  $\min(|X'|, |Y'|)$ .

We use the following well-known results:

**Lemma 1.** *For any line  $\mathcal{L}$  in the plane and finite set of points, it is possible to find another line  $\mathcal{M}$  which simultaneously splits the points in both halfplanes in any desired proportions.*

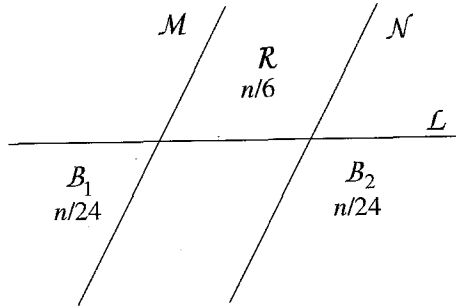
**Lemma 2.** [4] *Among any sequence of real numbers of length  $n$ , there is either an ascending or a descending subsequence of length  $\sqrt{n}$ .*

We will work in the two-color case, where  $X$  is to be chosen from among  $n/2$  blue, and  $Y$  from among  $n/2$  red points.

### Theorem 1.

- (i) *Given  $n/2$  red and  $n/2$  blue points, there exists a crossing family of size at least  $\sqrt{n/24}$ .*
- (ii) *Given  $n$  uncolored points, there exists a crossing family of size at least  $\sqrt{n/12}$ .*

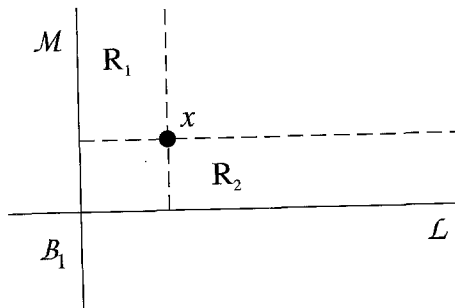
**Proof.** Our strategy in proving (i) has three steps.

Fig. 1. The  $H$ -picture.

**Step 1.** This is a preliminary step where the plane is partitioned by three lines (as depicted in Figure 1) so that certain regions have linearly many points of particular colors.

Specifically, first find a line  $\mathcal{L}$  such that at least  $n/4$  of the reds are on one side and at least  $n/4$  blues on the other by moving a horizontal  $\mathcal{L}$  down from  $y = +\infty$  until  $n/4$  of the first color, say red, are above it. Discard the blue points above  $\mathcal{L}$  and the red points below it. Second, use Lemma 1 to find a line  $\mathcal{M}$  such that exactly  $n/24$  of the red and  $n/24$  of the blue points are to the left of  $\mathcal{M}$ . Finally, take a line  $\mathcal{N}$  parallel to  $\mathcal{M}$  at  $x = +\infty$  and move it to the left until  $n/24$  of the first color, say blue, are on its right. See Figure 1. The region  $\mathcal{R}$  contains at least  $n/6$  red points, and the regions  $\mathcal{B}_1$  and  $\mathcal{B}_2$  both at least  $n/24$  blue points.

**Step 2.** For convenience, apply an affine transformation such that  $\mathcal{M}$  and  $\mathcal{N}$  are vertical. Order the reds in  $\mathcal{R}$  from left to right. By Lemma 2 there exists either an ascending or a descending subsequence  $R$  of length  $\sqrt{n/6}$ . Without loss of generality assume that  $R$  is *descending*. Then observe that  $R$  avoids  $\mathcal{B}_1$ .

Fig. 2.  $x$  splits  $R$  into two parts.

**Step 3.** Consider the middle points  $x$  of  $R$  breaking it into two parts  $R_1$  and  $R_2$ , each a descending sequence of length  $\sqrt{n/24}$ . See Figure 2.

Consider the positions of the blue points in  $\mathcal{B}_1$  expressed in polar coordinates  $(r, \theta)$  with  $x$  as the origin (and  $\theta$  measured counterclockwise), and order them as  $\{b_i\}$  (for  $i=1, \dots, n/24$ ) in decreasing distance  $r_i$  from  $x$ . By Lemma 2 there exists a subsequence  $B = \{b_{k_i}\}$  (for  $i=1, \dots, \sqrt{n/24}$ ) whose angles  $\theta_{k_i}$  are either decreasing or increasing. Say they are *increasing*. We claim that  $B$  avoids  $R_1$ . For consider two points  $b_{k_i}$  and  $b_{k_j}$  of  $B$  with  $i < j$ . From the conditions on  $B$  it follows that  $b_{k_j}$  is to the right of  $b_{k_i}$  and below the line subtended by  $x$  and  $b_{k_1}$ . Thus the line spanned by  $b_{k_i}$  and  $b_{k_j}$  avoids the region containing  $R_1$ .

Applying Corollary 1, the theorem follows. The only change for the uncolored case (ii) is that  $\mathcal{L}$  may be found without discarding half the points. ■

The above procedure provides an  $O(n \log n)$ -time algorithm for constructing a crossing family since one can apply Lemmas 1 and 2 in this time. (For Lemma 1 cf. [3].)

### 3. A characterization

In this section we examine conditions which characterize when two sets can be crossed and when they are mutually avoiding.

Consider red points  $X$  and blue points  $Y$  separated by a line  $\mathcal{L}$ . We say a red point  $x$  sees a blue point  $y$  at rank  $i$  if  $y$  is the  $i^{\text{th}}$  blue point counterclockwise as seen from  $x$ . And vice versa. Then we say  $X$  and  $Y$  obey the *rank condition* if there exist labelings  $x_1, \dots, x_s$  and  $y_1, \dots, y_s$  of  $X$  and  $Y$  such that for all  $i$ ,  $x_i$  sees  $y_i$  at rank  $i$  and vice versa. For the *strong rank condition*, the labelings must be such that  $x_i$  sees  $y_j$  at rank  $j$  for all  $i$  and  $j$ .

**Proposition 1.** *Let  $X$  and  $Y$  be  $s$  red and  $s$  blue points separated by a line. Then:*

- (1)  *$X$  and  $Y$  can be crossed if and only if they obey the rank condition.*
- (2)  *$X$  and  $Y$  are mutually avoiding if and only if they obey the strong rank condition.*

Since the strong rank condition implies the rank condition, this gives:

**Corollary 1.** *A pair of sets can be crossed if they are mutually avoiding and of equal cardinality.*

**Proof.** (1) Say the line  $\mathcal{L}$  is vertical, with reds  $X$  on the left and blues  $Y$  on the right.

Assume first that  $X$  and  $Y$  can be crossed. Let  $l_1, \dots, l_s$  be the line segments of a complete crossing family in order of increasing slope. Label the red endpoint of  $l_i$ ,  $x_i$ , and the blue endpoint  $y_i$ . Since  $l_1, \dots, l_{i-1}$  are of lesser slope than  $l_i$ , and intersect it,  $x_i$  sees  $y_1, \dots, y_{i-1}$  before it sees  $y_i$ . Similarly,  $x_i$  sees  $y_{i+1}, \dots, y_s$  after  $y_i$  and thus it sees  $y_i$  at rank  $i$ . For the same reason,  $y_i$  sees  $x_i$  at rank  $i$ .

Assume now that there exist labeling  $x_i, y_i$  satisfying the rank condition. We prove by induction on  $s$  that the family  $\{x_i y_i\}_i$  of line segments is a crossing family. The case  $s=1$  is trivial.

Consider the line  $\ell_s$  extending the segment  $x_s y_s$ . By the rank condition,  $X - x_s$  and  $Y - y_s$  lie on opposite sides of this line. Hence  $x_s y_s$  intersects  $x_i y_i$  if it intersects  $\ell_i$ . Also, the slope of  $x_i y_i$  is less than that of  $x_s y_s$  for all  $i < s$ .

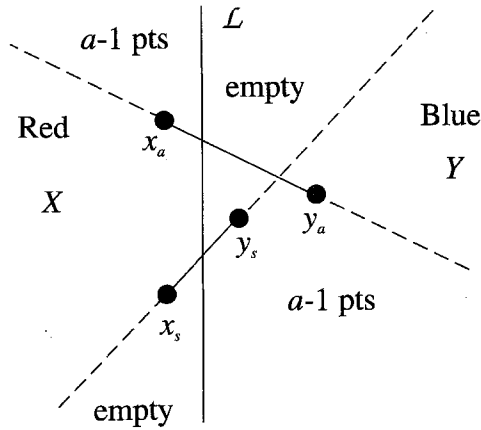


Fig. 3. The picture when  $x_a y_a$  is above  $x_s y_s$ .

Let  $A$  be the set of all line segments that do not intersect  $x_s y_s$ ; order the members of  $A$  with respect to their  $\mathcal{L}$ -intercepts. If  $A$  is nonempty then without loss of generality it contains a line segment whose  $\mathcal{L}$ -intercept is above that of  $x_s y_s$ ; then choose  $a$  such that  $x_a y_a$  has the highest  $\mathcal{L}$ -intercept in  $A$ . See Figure 3. Then the line  $\ell_a$  extending  $x_a y_a$  does not intersect  $x_s y_s$ . So there exist  $a-1$  red points above  $\ell_a$  and  $a-1$  blue points below it. But  $y_s$  is among these blue points while  $x_s$  is not among the red ones. Thus there exists  $b$  so that  $x_b$  and  $y_b$  are both above  $\ell_a$ . Then  $x_b y_b$  does not intersect  $x_s y_s$  and has a higher  $\mathcal{L}$ -intercept than  $x_a y_a$ , contrary to assumption. Hence  $A$  is empty, and  $x_s y_s$  intersects all  $x_i y_i$ .

To prove that  $x_i y_i$  intersects  $x_j y_j$  for all  $i < j < s$ , we observe that since the slope of  $x_s y_s$  is greater than that of any other segment, the rank condition is preserved upon deletion of  $x_s$  and  $y_s$ , with the same labeling  $x_1, \dots, x_{s-1}$  and  $y_1, \dots, y_{s-1}$ . Hence by induction  $\{x_i y_i\}_1^{s-1}$  is a crossing family.

(2) The order in which a point  $x$  sees two points  $y_1$  and  $y_2$  is determined by which side of the line through them  $x$  lies. If  $Y$  avoids  $X$  then each pair  $y_i, y_j$  is seen in the same order by all  $x \in X$ , and a similar conclusion holds if  $X$  avoids  $Y$ ; hence if  $X$  and  $Y$  are mutually avoiding then they satisfy the strong rank condition.

If on the other hand the sets are not mutually avoiding, say  $Y$  does not avoid  $X$ , then there is a pair of points in  $Y$  subtending a line through the convex hull of  $X$ , and this pair is seen in a different order by the points of  $X$  to each side of that line. Hence the strong rank condition fails. ■

#### 4. Parallel families

We use the term “parallel” to describe a pair of nonintersecting line segments whose extensions intersect outside both segments. We say that a family of line segments is parallel if every pair of the segments is parallel.

The following can be shown in the manner of Proposition 1:

**Proposition 2.** *Let  $X$  and  $Y$  be two sets, of  $s$  points each, separated by a line. Then  $X$  and  $Y$  can be paired up to form a parallel family if and only if there exist labeling  $x_1, \dots, x_s$  and  $y_1, \dots, y_s$  of  $X$  and  $Y$  such that for all  $i$ ,  $x_i$  sees  $y_i$  at rank  $i$  and  $y_i$  sees  $x_i$  at rank  $s+1-i$ . In particular, if  $X$  and  $Y$  are mutually avoiding then  $X$  and  $Y$  can be so paired.*

The problems of finding large parallel and large crossing families are equivalent:

**Theorem 2.** *Let  $c(n)$  (resp.  $p(n)$ ) denote the minimum number of segments in a maximum crossing (parallel) family, among all configurations of  $n$  blue and  $n$  red points separated by a line, with all  $2n$  points in general position. Then  $c(n)=p(n)$ .*

**Proof.** Consider a configuration of points with  $n$  points either side of the  $y$ -axis and the transformation  $f$  given by  $(x, y) \mapsto (1/x, y/x)$ . This carries the points to a new configuration such that if segments  $b_1r_1$  and  $b_2r_2$  intersect and meet the  $y$ -axis, then segments  $f(b_1)f(r_1)$  and  $f(b_2)f(r_2)$  are parallel and meet the  $y$ -axis, and vice versa. ■

## 5. Mutually avoiding sets in higher dimensions

In this section we show that there are polynomial-sized mutually avoiding sets in arbitrary dimensions. A hyperplane *stabs* a set in  $\mathbb{R}^d$  if it intersects the convex hull of that set. The *stabbing number* of a collection of sets is the maximum number of sets that any hyperplane stabs. We use the following result of Matoušek:

**Lemma 3.** [5] *Let  $P$  be a set of  $n$  points in  $\mathbb{R}^d$  and let  $r \leq n$ . Then there exists a subset  $P' \subseteq P$  of at least  $n/2$  points and a partition  $\{P_1, \dots, P_m\}$  of  $P'$  with  $|P_i| = \lfloor n/r \rfloor$  for all  $i$  and with stabbing number  $O(r^{1-1/d})$ .*

**Theorem 3.** *Any set of  $n$  points in  $\mathbb{R}^d$  contains a pair of mutually avoiding subsets each of size  $\Omega(n^{1/(d^2-d+1)})$ .*

**Proof.** Say we apply the above result with parameter  $r$  yielding a partition of  $P'$  into blocks  $P_1, \dots, P_m$ . Note that  $m$  is  $\Theta(r)$ . The points of each  $P_i$  generate  $O(n^d/r^d)$  hyperplanes, and each of these hyperplanes stabs  $O(r^{1-1/d})$  subsets. Thus there are at most  $O(n^d r^{2-d-1/d})$  stabblings in all.

Associate every stabbing with the (unordered) pair of blocks consisting of the block generating the hyperplane, and the block which is stabbed by it. Since there are  $\Theta(r^2)$  pairs of blocks, some pair has only  $n^d r^{-d-1/d}$  such mutual stabblings. If  $r$  is chosen to be approximately  $n^{(d^2-d)/(d^2-d+1)}$  then this pair has at most  $n/2r$  mutual stabblings. Each stabbing is created by a hyperplane which can be eliminated by removing one point from one of the blocks. The depleted blocks are each of size at least  $n/2r = \Omega(n^{1/(d^2-d+1)})$ , and are mutually avoiding. ■

We can use the above result to find an analogue of a polynomial-sized crossing family in  $\mathbb{R}^d$ : a collection of  $d$ -simplices such that every two simplices intersect and have disjoint vertex sets. We omit the construction.

## 6. Discussion

We believe our lower bound on the size of maximum crossing families can be improved. Our best upper bound is linear: at most  $n/2$  points used for the uncolored case (for example for non-convex points) and at most  $3n/8$  in the colored case. For the latter consider the arrangement of sixteen points in Figure 4. These ratios can be obtained for arbitrarily large  $n$  by splitting points suitably. Regarding the behavior of “generic” sets of points, we note that  $n$  points (colored or not) chosen at random in the unit disk, almost surely have a linear-sized crossing family. We omit the details.

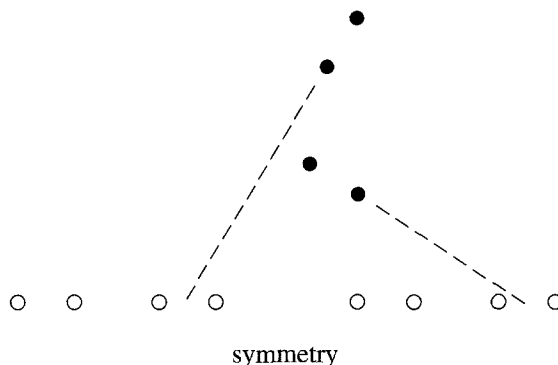


Fig. 4. Arrangement for upper bound for two colored case: 4 more black points are located symmetrically below the whites.

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